BEE401

Fourth Semester B.E/B.Tech. Degree Examination, June/July 2025 Electric Motors

Max. Marks:100

Note: 1. Answer any FIVE full questions, choosing ONE full question from each module.
2. M: Marks, L: Bloom's level, C: Course outcomes.

| | | Module – 1 | M | L | C |
|---|----------|---|----|-----|-----------------|
| | | What is back emf? Derive the armature torque of a DC motor. | 6 | L1 | CO ₁ |
| 1 | a. | What is back emf? Derive the affinitive torque of a Be interest | 6 | L2 | CO1 |
| | b. | • | | | |
| | | i) Shunt motor | | | |
| | | ii) Series motor | | | |
| | | iii) Cumulatively compounded motor | | | |
| | | iv) Differentially compound motor. What are the losses that occur in DC machines? Draw the power flow diagram | 8 | L2 | CO ₁ |
| | c. | What are the losses that occur in Be internal | | | |
| | | of DC motor. | | | 001 |
| _ | | Explain the operation of four point starter with neat diagram, mention its | 6 | L1 | CO1 |
| 2 | a. | | | T 0 | COI |
| | 1. | Explain the fields test on series motor and explain the method to find out | 6 | L2 | CO1 |
| | b. | 200 | | T 2 | CO1 |
| | - | t is registance of 10 between its ferminals drives a fair, the | 8 | L3 | COI |
| | c. | | | | |
| | | 200 mm and takes 15A The speed of the land is to be faised to 375 april 19 | | | |
| | | supply voltage control estimates the supply voltage required. | | | |
| | | | | | |
| | | Module – 2 | 10 | L1 | CO2 |
| 3 | a. | With the help of neat diagram, explain how efficiency of DC motor can be | 10 | | |
| , | a. | determined by the retardation test. | 10 | L2 | CO2 |
| | b. | | 10 | | |
| | 0. | · Fallowing recilife When the machine acted as a second | | | |
| | | as a generator, calculate the efficiency of motor and generator. | | | |
| | | as a generator, calculate the efficiency of motor and generator. Motor: Armature voltage: 590V, armature current: 56A voltage drop across | | | |
| | | field winding: 40V | | | |
| | | Compretor: Armsture voltage: 400 V, Alliature current: 1123 | | | |
| | | drop: 40V, resistance of each armature: 0.322 1011. | | | |
| | | OR | 4 | L1 | CO |
| T | a. | What is slip in induction motor? Explain its significance. | 8 | L2 | CO |
| + | b. | | | | |
| | 0. | A 12 pole, 50 Hz, 3\(\phi\) IM has rotor resistance of 0.152 and stand of 0.25 PS phase. On full load it is running at a speed of 480 rpm. The rotor of 0.25 PS phase. On full load it is cheeryed to be 32V, calculate: | | | |
| | | of 0.25 PS phase. On full load it is fulling at a speed of induced emf per phase at stand still is observed to be 32V. calculate: | | | |
| | | i) Starting torque | | | |
| | | ii) Fill load torque | | | |
| | | iii) Maximum torque | | | |
| | | iv) Speed at maximum torque. | 8 | L2 | CO |
| + | <u> </u> | iv) Speed at maximum torque. Explain and derive the torque equation for 3-φ induction motor and derive the | | | |
| | c. | condition for maximum torque. | | | |
| | | 1 of 2 | | | |

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|---|----------|---|----|--------|-------|
| | | Module - 3 | | | |
| 5 | 5 a | land of a second of a second of a polymer. | 10 | L1 | CO4 |
| | b | | 10 | L2 | CO3 |
| | | OR | | | |
| 6 | a. | working of deep bar rotor induction motor. | 10 | L1 | CO3 |
| | b. | A 415V, 29.84KW, 50Hz delta connected motor gave the following test data: No load test: 415V, 21A, 1250W Blocked rotor test: 100V, 45A, 2730W Construct the circle diagram and determine: i) Line current and power factor for rated output. ii) The maximum torque. Assume stator and rotor copper losses are equal at stand still. | 10 | L2 | CO4 |
| | | Module – 4 | | | |
| 7 | a. | Explain in detail auto transformer method of starting a squirrel Cage induction motor. | 10 | L2 | CO6 |
| | b. | Mention the different methods of speed control of 3-\$\phi\$ induction motor. Describe any two methods. | 10 | L2 | CO5 |
| | 1 | OR | | | T -:- |
| 3 | a. | Explain double field revolving theory as applied to 1-φ phase induction motor and prove that it cannot produce any starting torque. | 10 | L1 | CO4 |
| | b. | Explain why 1 - \(\phi \) induction motor is not self starting. | 5 | L2 | COS |
| | c. | Briefly explain torque speed characteristics of capacitor split phase motor. Mention the applications of capacitor split phase motors. | 5 | L2 | COS |
| | | Module – 5 | | | |
| _ | | What are v and inverted v curves? Sketch them and explain their significance. | 10 | L2 | CO |
| | a. b. | Explain the operation of synchronous motor at constant load variable | 10 | L2 | CO |
| | | excitation. OR | | | |
|) | a. | Explain the principle of operation of linear induction motor. List the some | 10 | L2 | CO |
| | | applications of it brief the working of linear conduction motor. | 5 | L2 | CO |
| 1 | b. | State the methods of starting synchronous motor. Explain any one details. Explain the importance of daraping winding in synchronous motor. | 5 | Li | _ |
| | c. | Explain the importance of the P | | | |