

## Time: 3 hrs.

Max. Marks: 100

## Module-1

- 1 a. Distinguish between open loop and closed loop control system with examples. (06 Marks)  
b. Find the transfer function of the electrical network shown in Fig.Q1(b) in phase load form:

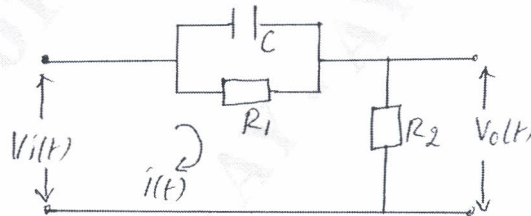


Fig.Q1(b)

**(06 Marks)**

- c. For the mechanism system shown in Fig.Q1(c):
- Draw the mechanical network
  - Write the differential equations
  - Draw electrical network by force voltage analogy.

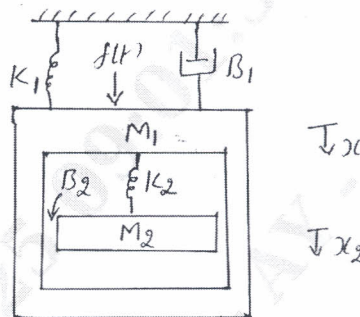


Fig.Q1(c)

**(08 Marks)**

OR

- 2 a. Define servo motor. Compare AC servomotor and DC servo motor. (04 Marks)  
b. For the mechanical system shown in Fig.Q2(b), obtain the equation of motion for masses

$M_1$  and  $M_2$  and find  $\frac{X_2(s)}{F(s)}$ .

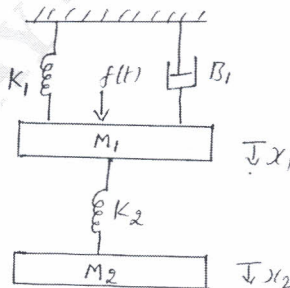


Fig.Q2(b)

**(08 Marks)**

**Important Note :**

1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
2. Any revealing of identification, appeal to evaluator and /or equations written eg.  $42+8=50$ , will be treated as malpractice.

- b. Draw the corresponding signal flow graph of given block diagram shown in Fig.Q4(b) and find  $\frac{C(s)}{R(s)}$ .

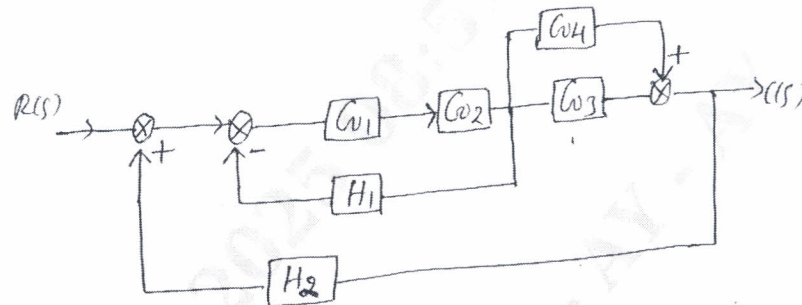


Fig.Q4(b)

- c. Explain Mason's gain formula indicating each term.

(08 Marks)

(04 Marks)

### Module-3

- 5 a. Define the following for an under damped second order system:  
 (i) Rise time (ii) Peak overshoot (iii) Settling time (06 Marks)  
 b. Derive an expression for under damped response of a second order feedback control system for unit step input. (08 Marks)  
 c. The characteristic equation of the system is given by  $s^4 + 22s^3 + 10s^2 + 2s + K = 0$ . Using RH criterion, find the range of K for which the system is stable. (06 Marks)

### OR

- 6 a. What are the difficulties encountered while assessing R-H criteria and how do you eliminate these difficulties? Explain with examples. (06 Marks)  
 b. Derive an expression for rise time and peak time for a second order system excited by a step input. (08 Marks)  
 c. Evaluate the static error constants for unity feedback system with  $G(s) = \frac{10}{s(1+0.1s)}$ . Obtain the steady state error when the input is  $r(t) = a_0 + a_1t + \frac{a_2t^2}{2}$ . (06 Marks)

### Module-4

- 7 a. Write notes on: (i) Break away point (ii) Asymptotes (04 Marks)  
 b. Show that part of root locus of a system with  $G(s)H(s) = \frac{K(s+3)}{s(s+2)}$  is a circle having centre  $(-3, 0)$  and radius at  $\sqrt{3}$ . (08 Marks)  
 c. Sketch the root locus plot for the open loop transfer function  $G(s)H(s) = \frac{K}{s(s+2)(s+3)}$ . (08 Marks)

### OR

- 8 a. Explain the angle and magnitude condition of root locus. (06 Marks)  
 b. Sketch the bodes magnitude and phase diagram for

$$G(s)H(s) = \frac{5}{s(1+0.5s)(1+0.05s)}$$

(08 Marks)