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17ME73

## Seventh Semester B.E. Degree Examination, June/July 2023 Control Engineering

Time: 3 hrs.

Max. Marks: 100

*Note: Answer any FIVE full questions, choosing ONE full question from each module.*

### Module-1

- 1 a. Sketch the basic components present in open loop and closed loop control systems. (08 Marks)
- b. What are the characteristics of Negative feedback? Why are they preferred? (08 Marks)
- c. Distinguish between Linear and Non-Linear control system. (04 Marks)

OR

- 2 a. Define : (i) Proportional controller. (ii) Derivative controller
- (iii) Integral controller (iv) P.I.D controller (08 Marks)
- b. Describe the effect of various controllers on system performance. (12 Marks)

### Module-2

- 3 a. Find the transfer function  $\frac{Q_1(s)}{T(s)}$  of the given mechanical rotational system.

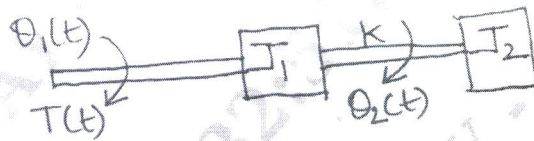


Fig. Q3 (a)

(10 Marks)

- b. Draw the F-V and F-C analogous circuit for the given system :

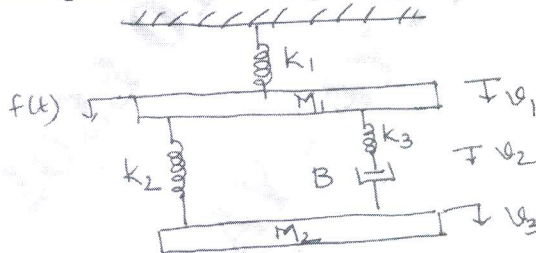


Fig. Q3 (b)

(10 Marks)

OR

- 4 a. Using Reducing technique, obtain overall transfer function of the block diagram shown in Fig. Q4 (a)

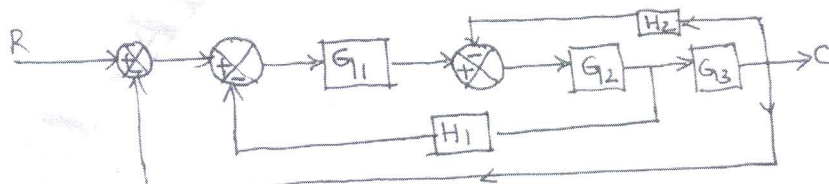


Fig. Q4 (a)

(10 Marks)

- b. Obtain overall transfer function  $\frac{C}{R}$  of the SFG shown in Fig.Q4 (b).

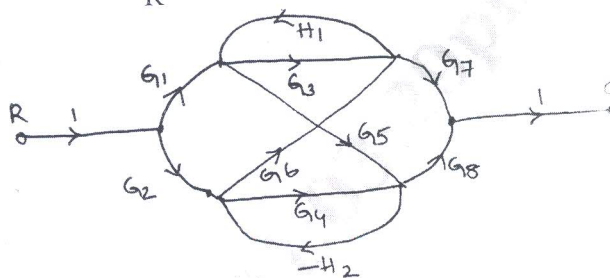


Fig. Q4 (b)

(10 Marks)

**Module-3**

- 5 a. Define : (i) Time response (ii) Transient response. (iii) Steady-state response (08 Marks)
- b. Consider the system shown in Fig. Q5 (b), where  $\xi = 0.5$ ,  $\omega_n = 4$  rad/sec. Find  
 (i)  $\omega_d$  (ii)  $t_r$  (iii)  $t_p$  (iv)  $M_p$  (v)  $t_s$

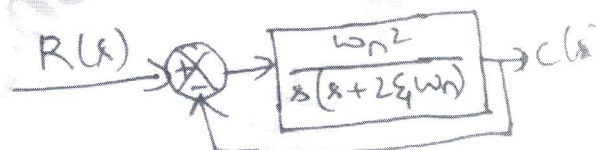


Fig. Q5 (b)

(12 Marks)

OR

- 6 Sketch the Root locus for the system with unity feedback system and whose open loop transfer function is  $G(s) = \frac{K}{s(s^2 + 6s + 10)}$ . (20 Marks)

**Module-4**

- 7 Sketch the Bode plot for the following transfer function and determine GM and PM. (20 Marks)
- $$G(s) = \frac{75(1 + 0.2s)}{s(s^2 + 16s + 100)}$$

OR

- 8 Sketch the Nyquist plot and therefore determine the stability of the closed loop system whose open loop transfer function is given by,  $G(s)H(s) = \frac{K}{s(s^2 + s + 2)}$ . (20 Marks)

**Module-5**

- 9 a. What is a Lead compensator and Lag compensator? When are they preferred? (08 Marks)
- b. Obtain the transfer function of the system :

$$\begin{Bmatrix} \dot{x}_1 \\ \dot{x}_2 \end{Bmatrix} = \begin{bmatrix} -5 & -1 \\ 3 & -1 \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} + \begin{Bmatrix} 2 \\ 5 \end{Bmatrix} u \text{ and } y = \begin{bmatrix} 1 & 2 \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix}.$$

(12 Marks)

OR

- 10 Transfer function of a system is given by :  
 $\frac{Y(s)}{U(s)} = \frac{2}{s^3 + 6s^2 + 11s + 6}$  by Gilberts test. (20 Marks)

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