

# CBCS SCHEME

15AE71

# Seventh Semester B.E. Degree Examination, June/July 2023 Control Engineering

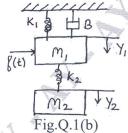
Time: 3 hrs.

Max. Marks: 80

Note: Answer any FIVE full questions, choosing ONE full question from each module.

# Module-1

- a. Explain closed loop control system with an example. What are the advantages and disadvantages of closed loop control system? (10 Marks)
  - b. Determine the transfer function  $Y_2(s)/F(s)$  of the system shown in Fig.Q.1(b). (06 Marks)



OR

2 a. Obtain the differential equations for the torsional system shown in Fig.Q.2(a). By using appropriate analogy obtain and draw the analogous force-voltage electrical network.

Fig.Q.2(a)

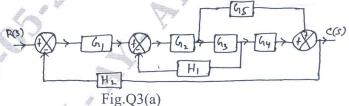
b. Derive the transfer function of an armature controlled dc motor.

(06 Marks)

(10 Marks)

Module-2

3 a. Reduce block diagram as shown in Fig.Q3(a).



Find out the overall gain using Mason's gain formula shown in Fig.Q3(b).

(08 Marks) 3(b).

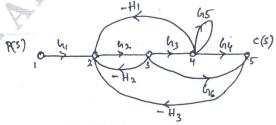


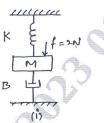
Fig.Q3(b) 1 of 2

(08 Marks)

#### OR

For a spring mass damper system shown in Fig.Q4 on experiment was conducted by applying a force of 2 Newtons to the mass. The response x(t) was recorded using an xy plotter and the experimental result is as shown in the Fig.Q4 below. Find the value of M, K and B.

(16 Marks)



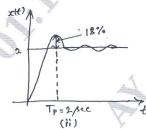


Fig.Q4

# Module-3

Draw the complete root locus diagram for the system with open-loop transfer function  $G(S)H(S) = \frac{K(s+1)}{s^2(s+3)(s+5)}$ . Determine the range of variation of K over which the system remain stable. (16 Marks)

# OR

Sketch the Bode plot for  $G(S)H(S) = \frac{2}{s(1+s)(1+0.2s)}$ . Also obtain Gain Margin and Phase Margin and cross over frequencies. (16 Marks)

#### Module-4

- 7 a. Derive the expression for resonant peak  $M_r$  and resonant frequency  $w_r$  for a standard second order system in terms of  $\xi$  and  $w_n$ . (10 Marks)
  - b. Find the open loop transfer function of a unity feedback second order control system for which resonant peak = 1.1 units and resonant frequency = 11.2 rad/sec. (06 Marks)

#### OR

For a open loop TF of a feedback control system

G(s)H(s) = 
$$\frac{k(1+2s)}{s(1+s)(1+s+s^2)}$$

Sketch the complete Nyquist plot and hence find the range of k for stability using Nyquist criterion. (16 Marks)

## Module-5

- 9 a. Explain the series and feedback compensation with block diagram. (08 Marks)
  - b. Explain the following: i) Lead compensator ii) Lag compensator. (08 Marks)

### OR

10 a. Write a note on Kalman and Gilberts test.

(06 Marks)

- b. Define the following terms:
  - i) State
  - ii) State variables
  - iii) State vector
  - iv) State space
  - v) State equation (10 Marks)