

17MT71

(10 Marks)

## Seventh Semester B.E. Degree Examination, July/August 2022 **Industrial Robotics**

Time: 3 hrs.

Max. Marks: 100

Note: Answer any FIVE full questions, choosing ONE full question from each module,

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		Module-1	
1	a.	Explain the brief history of robotics.	(10 Marks)
	b.	List the three types of drive systems used in robots and give comparison between	them.
			(10 Marks)
		OR	
2	a.	Define the following: i) Automation ii) Robotics and industrial robot	
		iii) Special resolution iv) Accuracy v) Repeatability.	(10 Marks)
	b.	With neat sketch, explain different configurations of robots.	(10 Marks)
		Module-2	
3	a.	List different types of sensors used in robotics and explain tactile and proximity	sensors.
			(10 Marks)
	b.	Explain different considerations in gripper selection and design.	(10 Marks)
		OR	
4	a.	What is D.H convention? Describe with neat diagram.	(10 Marks)
	b.	Explain in brief: i) Vaccum grippers ii) Mechanical grippers.	(10 Marks)
		Module-3	
5	a.	Explain the limitations and advantages of lead through programming.	(10 Marks)
	b.	Explain the functions of machine vision system with neat block diagram.	(10 Marks)
		OR	
6	a.	Describe different goals of Artificial Intelligence (AI).	(10 Marks)
•	b.	Explain the different applications of machine vision system in robotics.	(10 Marks)
		Module-4	
7	a.	1	(10 Marks)
	b.	Describe with neat sketch standard robot cell layouts.	(10 Marks)
		OR	
8	a.	Explain any two applications of robot in material handling applications.	(10 Marks)
		List out and describe different considerations in choosing the robot for mater	
		applications.	(10 Marks)
		Module-5	
9	a.	Explain compliance and Remote Centre Compliance (RCC).	(10 Marks)
	b.	Explain in brief part presentations methods in assembly operations.	(10 Marks)
		OR	
10	a.	How robots can be used to perform inspection? Explain.	(10 Marks)
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b. Write a note on following processing operations of robot

i) Spot welding ii) Continuous arc welding.