

CBCS SCHEME

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17MT34

Third Semester B.E. Degree Examination, July/August 2022 Control Systems

Time: 3 hrs.

Max. Marks: 100

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- 1 a. Define a control system and explain the types of control system with suitable examples. (10 Marks)
- b. Develop the mathematical equation and obtain transfer function $\frac{Y_2(s)}{F(s)}$ of the system shown in Fig Q1(b)

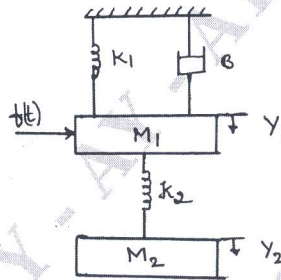


Fig Q1(b)

(10 Marks)

OR

- 2 a. Obtain the differential equations and draw the electric network using force – voltage analogy for the given system. (Ref. Fig Q2(a)).

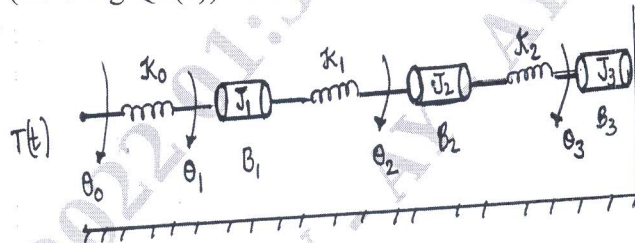


Fig Q2(a)

(10 Marks)

- b. Identify the transfer function of the system show in Fig Q2(b), by block diagram reduction methods.

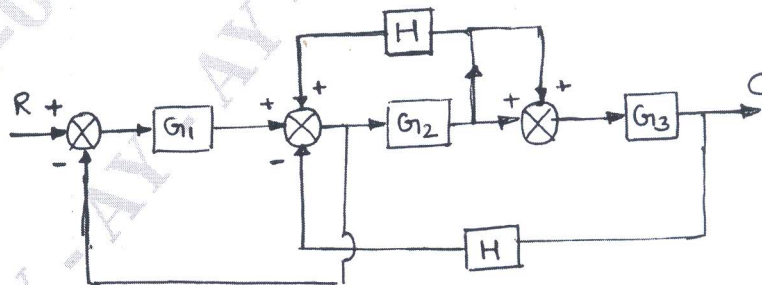


Fig Q2(b)

(10 Marks)

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.

Module-2

- 3 a. Using Mason's gain formula, find the gain of the following system in Fig Q3(a).

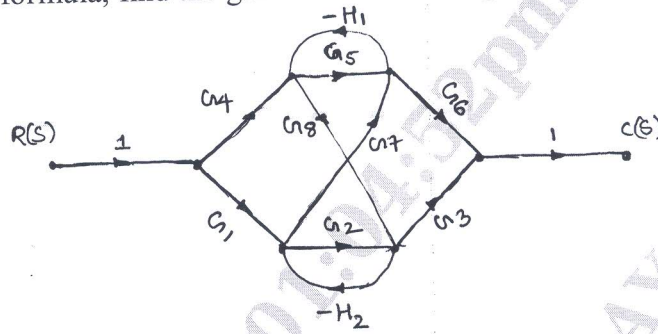


Fig Q3(a)

(10 Marks)

- b. Construct the signal flow graph for the following set of system equations.

$$Y_2 = G_1 Y_1 + G_3 Y_3$$

$$Y_3 = G_4 Y_1 + G_2 Y_2 + G_5 Y_3$$

$$Y_4 = G_6 Y_2 + G_7 Y_3$$

where Y_4 is output, Find transfer function $\frac{Y_4}{Y_1}$.

(10 Marks)

OR

- 4 a. Discuss the various standard input test signal used in the control system analysis. (07 Marks)
- b. Determine the response of a first order system with transfer function $\frac{C(s)}{R(s)} = \frac{1}{1 + Ts}$ by subjected unit step input and sketch the system response. (13 Marks)

Module-3

- 5 a. For a system with characteristics equation $s^6 + 3s^5 + 4s^4 + 6s^3 + 5s^2 + 3s + 2 = 0$, examine stability by means of Routh criterion. (10 Marks)
- b. Determine the stability of the systems represented by the characteristics equation $s^6 + 3s^5 + 5s^4 + 9s^3 + 8s^2 + 6s + 4 = 0$ by means of the Routh Criterion. Determine the number of roots lying in right half of s-plane. (10 Marks)

OR

- 6 The open loop transfer of a unity feedback system is $G(s) = \frac{1}{s(s+3)(s+5)}$. Determine closed loop dominant poles, damped natural frequency and gain K for the damping ratio 0.6. (20 Marks)

Module-4

- 7 The open loop transfer function of an unity feedback system is $G(s) = \frac{K}{s(1+0.1s)(1+s)}$. Determine the value of K so that gain margin is +30dB and phase margin is 30°. (20 Marks)

OR

- 8 Apply Nyquist stability criterion to the system with open loop transfer function $G(s)H(s) = \frac{40}{(s+4)(s^2+2s+2)}$ and ascertain its stability. (20 Marks)

Module-5

- 9 a. Obtain the appropriate state model for a system represented by an electric circuit in Fig Q9(a)

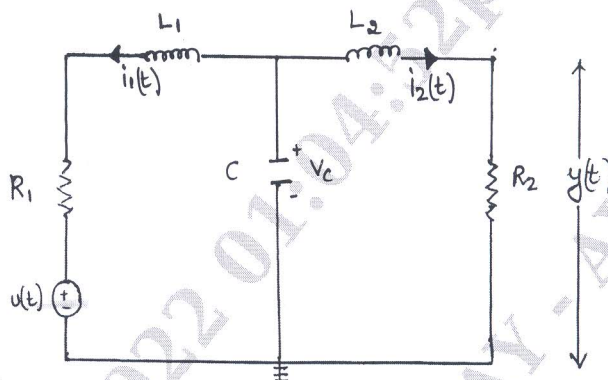


Fig Q9(a)

(10 Marks)

- b. Obtain the state transition matrix for the following system

$$\begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \end{bmatrix} = \begin{bmatrix} -1 & -0.5 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} + \begin{bmatrix} 0.5 \\ 0 \end{bmatrix} U$$

(10 Marks)

OR

- 10 a. Explain the derivation of transfer function from the state model and mention the advantages of phase variable. (10 Marks)
- b. Find the transfer function for a system having state model as given below :

$$\dot{X} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix} X + \begin{bmatrix} 1 \\ 0 \end{bmatrix} U$$

$$Y = [1 \ 0] X$$

(10 Marks)
