

Module-3

- 5 a. Explain Routh – Hurwitz's criterion and its limitations. (08 Marks)
 b. Find the range of value of 'K' so that system with the following characteristic equation will be stable $F(s) = s^4 + 5s^3 + 5s^2 + 4s + k = 0$. (08 Marks)

OR

- 6 a. Write general steps to solve the problems on root locus. (06 Marks)
 b. Draw the approximate root locus diagram for a closed loop system whose loop transfer function is given by

$$G(s)H(s) = \frac{K}{s(s+5)(s+10)} \quad (10 \text{ Marks})$$

Module-4

- 7 a. List the advantages and disadvantages of frequency domain analysis. (06 Marks)
 b. For a unity feedback system

$$G(s) = \frac{800(s+2)}{s^2(s+10)(s+40)} \quad \text{Sketch the bode plot. Comment on Stability.} \quad (10 \text{ Marks})$$

OR

- 8 For a certain control system

$$G(s)H(s) = \frac{K}{s(s+2)(s+10)} \quad \text{Select the Nyquist plot and hence calculate the range of values of 'K' for stability.} \quad (16 \text{ Marks})$$

Module-5

- 9 a. List the properties of state transition matrix. (06 Marks)
 b. Find the state space representation of the circuit diagram shown in Fig. Q9(b). Take V_s as the input and i_x as the output. (10 Marks)

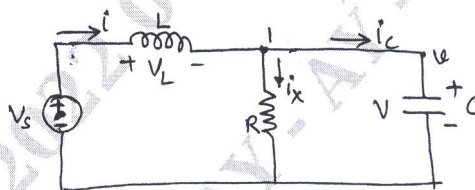


Fig. Q9(b)

OR

- 10 a. Define : i) State ii) State vector iii) State space iv) State variable. (08 Marks)
 b. Derive the transfer function for state model. (08 Marks)
