Important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.

15MT34

Third Semester B.E. Degree Examination, Feb./Mar. 2022 Control Systems

Max. Marks: 80

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- a. Define a Control System. List merits and demerits of Open loop and Closed loop system. Explain both the systems with neat block diagrams. (08 Marks)
 - b. For the Mechanical system shown in Fig. Q1(b), find the transfunction $X_1(s)/F(s)$.

(08 Marks)

OR

- 2 a. State block diagram reduction technique rules with neat diagram. (08 Marks)
 - b. For the rotational mechanical system shown in Fig. Q2(b), draw electrical network based torque current analogy. Give all the relevant performance equations. (08 Marks)

Fig. Q2(b)
$$T(4) \xrightarrow{T(4)} J_1 \xrightarrow{K_1} J_2 \xrightarrow{K_2} J_2 \xrightarrow{K_3} J_2 \xrightarrow{K_4} J_3 \xrightarrow{K_4} J_4 \xrightarrow{K_5} J_4 \xrightarrow{K_1} J_2 \xrightarrow{K_2} J_3 \xrightarrow{K_3} J_4 \xrightarrow{K_4} J_4 \xrightarrow{K_5} J_5 \xrightarrow{K_4} J_5 \xrightarrow{K_5} J_5 \xrightarrow{K_4} J_5 \xrightarrow{K_5} J_5 J_5 \xrightarrow{K_5} J_5 J_5 \xrightarrow{K_5} J_5 \xrightarrow{K_5} J_5 \xrightarrow{K_5} J_5 \xrightarrow{K_5} J_5 J_5 \xrightarrow{K_5} J_5 J_5 J_5 J_5 \xrightarrow{K_5} J_5 J_5 J_5 J_5 J_5 J_5 J_5$$

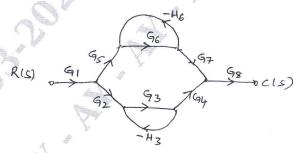
Module-2

a. State and explain the Mason's gain formula.

(08 Marks)

b. Find $\frac{C(s)}{R(s)}$ by using Mason's gain formula.

(08 Marks)



OR

- 4 a. Derive expression for peak time 'tp' and peak over shoot Mp of an under damped second order control systems subjected to step input. (08 Marks)
 - b. For a system $G(s)H(s) = \frac{K}{s^2(s+2)(s+3)}$. Find the value of 'K' to limit steady state error to

10% when input to system is $1 + 10t + \frac{40}{2}t^2$.

(08 Marks)

Module-3

5 a. Explain Routh – Hurwitz's criterion and its limitations.

(08 Marks)

b. Find the range of value of 'K' so that system with the following characteristic equation will be stable $F(s) = s^4 + 5s^3 + 5s^2 + 4s + k = 0$. (08 Marks)

OR

6 a. Write general steps to solve the problems on root locus.

(06 Marks)

b. Draw the approximate root locus diagram for a closed loop system whose loop transfer function is given by

G(s) H(s) =
$$\frac{K}{s(s+5)(s+10)}$$
.

(10 Marks)

Module-4

7 a. List the advantages and disadvantages of frequency domain analysis.

(06 Marks)

b. For a unity feedback system

$$G(s) = \frac{800(s+2)}{s^2(s+10)(s+40)}$$
. Sketch the bode plot. Comment on Stability. (10 Marks)

OR

8 For a certain control system

 $G(s) \ H(s) = \frac{K}{s(s+2)(s+10)} \ . \ Select \ the \ Nyquist \ plot \ and \ hence \ calculate \ the \ range \ of \ values \ of \ 'K' \ for \ stability.$

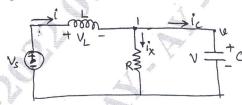
Module 5

a. List the properties of state transition matrix.

(06 Marks)

b. Find the state space representation of the circuit diagram shown in Fig. Q9(b). Take V_S as the input and i_X as the output. (10 Marks)





OR

- 10 a. Define: i) State ii) State vector iii) State space iv) State variable. (08 Marks)
 - b. Derive the transfer function for state model.

(08 Marks)

* * * * *