

## GBGS SCHEME

17EC42

## Fourth Semester B.E. Degree Examination, July/August 2021 Signals and Systems

Time: 3 hrs.

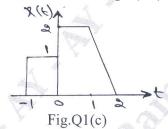
Max. Marks:100

Note: Answer any FIVE full questions.

- 1 a. Distinguish between:
  - i) Periodic and non-periodic signals
  - ii) Even and odd signals.

(04 Marks)

- b. Determine whether the following systems are linear, causal, dynamic, time-variants and stable. i) y(n) = 3x(n-1) ii)  $y(t) = x(t^2)$ . (08 Marks)
- c. Given the signal x(t) as shown, sketch the following: i) x(-2t+3) ii) x(t/2-2).



(08 Marks)

- 2 a. Check whether the following signals are periodic or not. If periodic, determine their fundamental period. i)  $x(t) = \cos 2t + \sin 3t$  ii)  $x(n) = \cos \left(\frac{\pi n}{5}\right) \sin \left(\frac{\pi n}{3}\right)$ . (06 Marks)
  - b. Sketch the even and odd parts of the following signal, x(t) = u(t+2) + u(t) 2u(t-1).

    (08 Marks)
  - c. Express: x(t) in terms of g(t), if x(t) and g(t) are as shown in Fig.Q2(c).

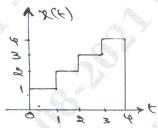
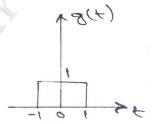


Fig.Q2(c)



(06 Marks)

- 3 a. Prove the following:
  - i)  $x(t) * \delta(t t_0) = x(t t_0)$
  - ii) x(n) \* h(n) = h(n) \* x(n).

(04 Marks)

- b. Compute the convolution integral of  $x(t) = e^{-3t}[u(t) u(t-2)]$  and  $h(t) = e^{-t}u(t)$ . (08 Marks)
- c. Evaluate y(t) = x(t) \* h(t). x(t) and h(t) are shown in Fig.Q3(c).

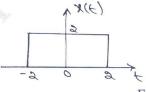


Fig.Q3(c) 1 of 3



(08 Marks)

- a. Evaluate y(n) = x(n) \* h(n). If x(n) and h(n) are given as:  $x(n) = \{2, \frac{4}{5}, -2, 1, 7\}$  and  $h(n) = \{2, 3, \frac{1}{5}, 4\}$ . (05 Marks)
  - b. Compute the convolution sum of  $x(n) = a^n u(n)$  and  $h(n) = b^n u(n)$ . (07 Marks) i) when a > b ii) when a < b iii) when a = b.
  - c. Determine the response of an LTI system with input  $x(n) = (\frac{1}{3})^n u(n)$  and impulse response h(n) = u(n) - u(n-5).
- 5 a. Calculate the step response of the LTI systems represented by following impulse responses.

i) 
$$h(n) = (\frac{1}{2})^n u(n-3)$$
 ii)  $h(t) = \begin{cases} 1, & -2 \le t \le 0 \\ 0, & \text{elsewhere} \end{cases}$  (06 Marks)

b. State any six properties of CTFS. (06 Marks) c. Determine the DTFS coefficients of  $x(n) = \sin\left(\frac{4\pi n}{21}\right) + \cos\left(\frac{10\pi n}{21}\right) + 1$ . Also sketch its

magnitude and phase spectrum. (08 Marks)

a. Check the following LTI system for memoryless, causality and stability:

i) 
$$h(t) = e^{t}u(-1,-t)$$
 ii)  $h(n) = \left\{ 2, 3, -1, 4 \right\}$ . (06 Marks)

b. Determine the Fourier series coefficients of the signal shown in Fig.6(b) and also plot  $|X \times (k)|$  and  $\leq X(k)$ .

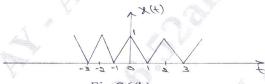


Fig.Q6(b) (08 Marks)

- c. State the following properties DTFS:
  - i) Time shifting
  - ii) Frequency shifting
  - iii) Convolution
  - iv) Modulation
  - v) Parseval's theorem
  - vi) Duality. (06 Marks)
- a. Determine the Fourier transforms of the following:

i) 
$$x(t) = e^{at}u(-t)$$
 ii)  $x(t) = e^{-a|t|}, a > 0.$  (08 Marks)

b. State and prove the following properties of DTFT:

c. Determine the Nyquist sampling rate and Nyquist sampling interval for the following signals:

i) 
$$x(t) = \frac{1}{2\pi} [\cos(4000\pi t)\cos(1000\pi t)]$$
 ii)  $y(t) = \sin C^2(200t)$ . (06 Marks)

a. State and prove the following properties of CTFT:

b. Determine the DTFTs of the following:

i) 
$$x(n) = {1 \choose 2}^n u(n-4)$$
 ii)  $x(n) = -a^n u(-n-1)$ . (08 Marks)

State the sampling theorem and briefly explain how to practically reconstruct the signal. (04 Marks)

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- Define region of convergence. Mention its properties. (04 Marks)
  - Using appropriate properties, find the z transforms of the following signals : b.

i) 
$$x(n) = n(n+1) u(n)$$
 ii)  $x(n) = n(\frac{1}{3})^{n+3} u(n+3)$ . (08 Marks) Evaluate the inverse  $Z$  – transform of the following for all possible ROCs.

$$X(z) = \frac{z(z^2 - 4z + 5)}{(z - 3)(z^2 - 3z + 2)}.$$
 (08 Marks)

- State and prove the following properties of Z-transform:
  - i) Time Reversal ii) Scaling in Z-domain. (06 Marks)
  - b. Find the Z-transform of  $x(n) = 2^n u(n) + 3^n u(-n-1)$  and draw its pole zero plot. (04 Marks)
  - Compute the response of the system : y(n) = 0.7y(n-1) 0.12y(n-2) + x(n-1) + x(n-2)to the input x(n) = n u(n). Also check whether the system is stable.