Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice Important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.

USN

Sixth Semester B.E. Degree Examination, Aug./Sept. 2020 Computer Graphics and Visualization

Time: 3 hrs. Max. Marks:100

Note: Answer any FIVE full questions, selecting at least TWO questions from each part.

PART - A

1	a.	What is graphics system?	Explain the five	major elements in the graphics	system with a neat
		diagram.			(06 Marks)
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b. Give the concept of pinhole camera. Explain how a point is projected in a pinhole camera.

Derive the expressions for projection and the angle of view. (08 Marks)

c. Write a program to construct a 2D Sierpinski Gasket by using 5000 points. (06 Marks)

2 a. What are the two color systems from the programmer's perspective, Give 2 API,s which supports each color system. Explain with neat diagrams. (10 Marks)

b. Explain Orthographic view and 2 dimensional viewing with their supporting API's and neat diagrams. (06 Marks)

c. What is hidden surface removal? Explain with its supporting API's. (04 Marks)

3 a. What are the different input modes, supported by input devices? (06 Marks)

b. What are the different ways of programming the event-driven inputs? (10 Marks)

c. Explain the concept of Double Buffering and how to use a timer in an OpenGL program.

(04 Marks)

4 a. Explain about i) Geometric objects ii) Lines iii) Affine sums iv) Convexity v) Planes. (10 Marks)

 b. What are affine transformations? Explain affine transformation for Translation, Rotation and scaling. (10 Marks)

PART - B

- 5 a. Explain:
 - i) Rotation about a fixed point
 - ii) General Rotation
 - iii) Rotation about an Arbitrary Axis with respect to concatenation of Transformations.
 (10 Marks)

b. What are Quaternions? How are they applied in rotation, Derive the supporting equation.

- the what are Quaternions? How are they applied in rotation, Derive the supporting equation.

 (10 Marks)
- 6 a. Explain Simple Projection Perspective projections and orthogonal projection. (08 Marks)
 - b. Derive the matrix for OpenGL perspective Transformations. (06 Marks)
 - c. Write a brief note on Projections and shadows. (06 Marks)
- 7 a. Explain the four basic types of Light sources in OpenGL. (08 Marks)
 - b. Explain Phong shading. (06 Marks)
 - c. Give the API's and specifications for different type of materials in OpenGL. (06 Marks)
- 8 a. Explain Cohen-Sutherland line clipping Algorithm, with an example in detail. (10 Marks)
- b. What is filling? Explain Scan-line filling algorithm for a polygon. (10 Marks)

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