



15MT71

(08 Marks)

Seventh Semester B.E. Degree Examination, Dec.2019/Jan.2020 Industrial Robotics

Time: 3 hrs. Max. Marks: 80 Note: Answer any FIVE full questions, choosing ONE full question from each module. Module-1 Define Automation. Explain three types of automation. (08 Marks) List the types of robot drive systems. Give the comparison between the three. (08 Marks) OR Define i) Spatial resolution ii) Repeatability Accuracy Compliance. iii) (08 Marks) With a neat sketch, explain robot configurations. (08 Marks) Module-2 Develop kinematics using homogenous transformations for scaling, translation and rotation 3 with example. (08 Marks) b. Write a note on Gripper mechanisms of mechanical gripper. (08 Marks) Explain in brief: i) Vaccum grippers ii) Magnetic grippers. (08 Marks) List the sensors used in robotics. Explain in brief tactile and proximity range sensors. (08 Marks) With a neat sketch, explain the machine vision system. 5 (08 Marks) Explain in brief lead through method of programming robot. (08 Marks) Write a note on WAIT, SIGNAL, DELAY commands. (08 Marks) b. Explain various methods of Knowledge representation in Artificial Intelligence (AI). (08 Marks) Module-4 a. Explain in detail robot cell layouts. (08 Marks)

b. What are the functions of Work cell controller? Explain.

- 8 a. How robot cycle time analysis is done? Explain. (08 Marks)
 - b. Write a short notes on: i) Electro Mechanical Relays ii) Programmable Controllers.
 (08 Marks)

a. Write a note on i) Spot welding Module-5 ii) Cont

- ii) Continuous arc welding. (08 Marks)
- Explain briefly part presentation methods in Robot Assembly Operation. (08 Marks)

OR

- 10 a. List and explain Robot Assembly Operations. (08 Marks)
 - b. How robots can be used to Perform Inspection? Explain. (08 Marks)

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