

15MA52

Fifth Semester B.E. Degree Examination, Dec.2019/Janl.2020 Computer Aided Design and Manufacturing

Time: 3 hrs.

Max. Marks: 80

Note: Answer any FIVE full questions, choosing ONE full question from each module.

Module-1

- a. Define CAD/CAM. With a neat diagram, explain the product cycle in a CAD/CAM environment. (08 Marks)
 - b. List out advantages and disadvantages of CAD/CAM.

(08 Marks)

OR

2 a. What are the functions of computer in CAD/CAM?

(08 Marks)

b. Explain the basic design process of CAD/CAM.

(08 Marks)

Module-2

3 a. Explain with neat sketches any two input devices.

(08 Marks)

b. What do you mean by wire frame modeling and solid frame modeling?

(08 Marks)

OR

4 a. Explain in detail basic modules and their function in graphics software.

(08 Marks)

b. Explain the following IGES, STEP, DXF, DMIS.

(08 Marks)

Module-3

- 5 a. Explain with sketches
 - i) FEM element types
 - ii) Mesh generation.

(08 Marks)

b. Discuss the pre-processing and post-processing stage in FEM.

(08 Marks)

OR

- 6 a. Define NC. Explain with sketches, the different types of motion control systems used in NC machines. (08 Marks)
 - b. Explain the importance of tool presetting in CNC. Use a typical example with suitable sketches and explain. (08 Marks)

Module-4

- 7 a. Explain turning centers and high speed machine tools in CAM programming. (08 Marks)
 - b. Explain turning machining centers in CAM programming.

(08 Marks)

OR

- 8 a. Explain the steps involved in development of a part program in NC/CNC machining.
 (08 Marks)
 - b. Write a manual part program for the following in Fig.Q8(b).

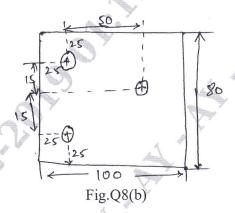


Plate thickness = 20mm,
Drill hole = 12.5mm,
Drill speed = 590rpm,
Drill feed role = 90mm/min,
Starting tool position= (25, 0, 50).

(08 Marks)

Module-5

9 a. Explain the types of sensors used in Robots.

b. Define a Robot. Briefly explain with neat sketches

- i) Polar co-ordinate configuration
- ii) Cartesian coordinate.

(08 Marks)

(08 Marks)

OR

- 10 a. Discuss the advantages, disadvantages and applications of Robots. (08 Marks)
 - b. Explain with neat sketch the different types of joints used in Robots.

(08 Marks)
