Sixth Semester B.E. Degree Examination, Dec.2019/Jan.2020

Computer Graphics and Visualization

Time: 3 hrs.

WOALORY

Max. Marks: 100

Note: Answer any FIVE full questions, selecting at least TWO questions from each part.

PART – A

- With a neat block diagram, explain the graphics pipeline architecture. (10 Marks) 1
 - Explain the concept of pinhole camera. Derive the expression for angle of view and also b. indicate the advantages and disadvantages.
- Write an OpenGL recursive program for 2D Sierpinski Gasket using Midpoint Method. 2 (10 Marks)
 - Explain the major groups of graphics function with at least two OpenGL functions for each. b. (10 Marks)
- Explain the various classes of logical input devices that are supported by OpenGL. Explain 3 the functionality of each. (10 Marks)
 - What is meant by measure and trigger of a device? Explain with neat diagram the various (10 Marks) models.
- Explain the OpenGL frames. a.

(06 Marks)

- Explain rotation and translation transformation with respect to 2-dimensions.
- (08 Marks) Explain the complete procedure of converting world object frame into camera frame using (06 Marks) model-view matrix.

PART - B

- Write an OpenGL program that allow you to rotate CUBE along x, y, z axis using button. 5 (10 Marks)
 - Explain the basic transformations in 3D and represent them in matrix form. (10 Marks) b.
- Bring out the deference between perspective and parallel projections. (08 Marks)
 - Define projection. Explain the functions used for the purpose in OpenGL:
 - i) Orthographic projections
 - ii) Perspective projections
- Describe the Phong lighting model and also indicate the advantages and disadvantages. 7 (10 Marks)
 - Explain the different methods of shading a polygon. Discuss any two. (10 Marks)
- Write Cohen-Sutherland line clipping algorithm. (10 Marks) 8 a.
 - Write Bresenham's line drawing algorithm.

(12 Marks)

(10 Marks)