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10AE71

Seventh Semester B.E. Degree Examination, June/July 2019
Control Engineering

Time: 3 hrs.

Max. Marks:100

Note: Answer any FIVE full questions, selecting at least TWO questions from each part.

PART - A

- 1 a. Explain the following briefly
 (i) plant (ii) process (iii) system (iv) disturbances (v) feedback control. (10 Marks)
 b. Discuss the requirement of an ideal control system. (10 Marks)
- 2 a. Find the transfer function $X_2(s)/F(s)$ for the system shown in Fig Q2(a).

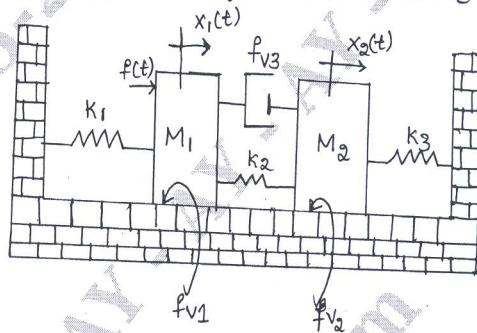


Fig Q2(a)

- b. Derive the transfer function of an armature controlled d.c motor. (10 Marks)
- 3 a. Determine the transfer function of a system whose block diagram is given in Fig Q3(a). Using the block diagram reduction technique. (10 Marks)

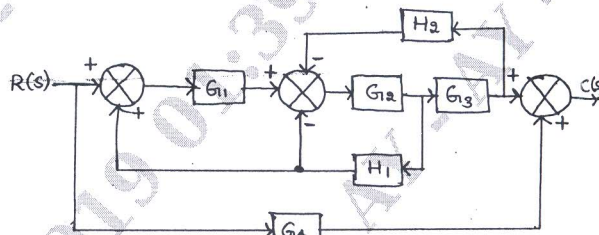


Fig Q3(a)

- b. Draw the corresponding signal flow graph for the block diagram shown in Fig. Q3(b). Also find $\frac{C(S)}{R(S)}$. (10 Marks)

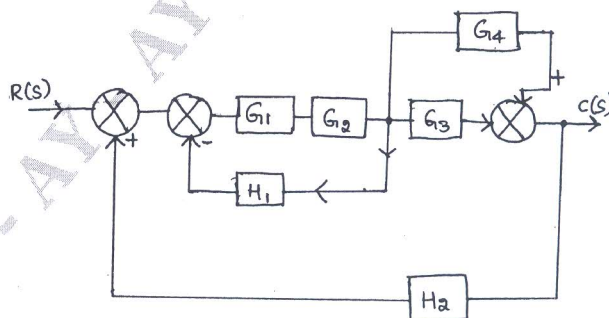


Fig Q3(b)

Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.
 2. Any revealing of identification, appeal to evaluator and /or equations written eg. 42+8 = 50, will be treated as malpractice.

- 4 a. Discuss the various standard inputs used in the control system analysis. (06 Marks)
 b. Derive the expression for unit step response of underdamped second order system. (08 Marks)
 c. A unity feedback system is characterized by an open-loop transfer function $G(s) = \frac{K}{s(s+10)}$. Determine the gain k , so that, the system will have a damping ratio of 0.5. For this value of k , determine the setting time, peak overshoot and time to peak overshoot for unit step input. (06 Marks)

PART - B

- 5 a. Sketch the Nyquist plot for system with $G(s)H(s) = \frac{(1+0.5s)}{s^2(1+0.1s)(1+0.2s)}$. comment on the stability. (14 Marks)
 b. Explain the use of M and N circles. (06 Marks)
- 6 Construct Bode diagram for a feedback control system having its open loop transfer function. $G(s)H(s) = \frac{100(10s+1)}{s(s+0.4)(s+1)(s+10)}$. Also determine gain margin and phase margin if the system stable. (20 Marks)
- 7 Sketch the root locus of the control system shown in the Fig Q7. (20 Marks)

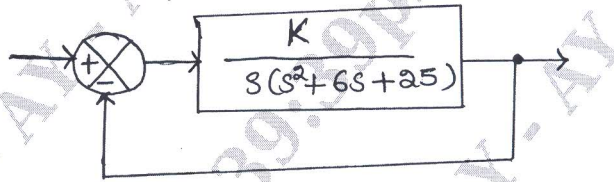


Fig Q7

- 8 a. Explain the following : (12 Marks)
 i) Series compensation
 ii) Parallel compensation
 iii) Series - parallel compensation.
 b. Obtain an expression for the frequency at which the phase lag is at its maximum for lag compensator. Also obtain their corner frequencies. (08 Marks)
