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USN		10BT61

Sixth Semester B.E. Degree Examination, Dec.2017/Jan.2018 Bioprocess & Automation

Time: 3 hrs.

Max. Marks: 100

Note: Answer FIVE full questions, selecting at least TWO questions from each part.

PART - A

- a. With a neat sketch, discuss on the working principle of different instruments used to measure pressure and temperature taking an example. (12 Marks)
 - b. Define process control. Describe the characterization of sensors in relation to the application for process control. (08 Marks)
- 2 a. With reference to the liquid level system, derive the first order lag function equation.

b. A mercury thermometer having a time constant of 0.1 min is placed in a temperature bath at 100° F and allowed to come to equilibrium with the bath. At time t = 0, the temperature of the bath begins to vary sinusoidally about its average temperature of 100° F with an amplitude of 2° F. If the frequency of oscillation is $\frac{10}{\pi}$ cycles/min, what is the phase lag?

(10 Marks)

3 a. Two non interacting tanks are connected in series as shown in Fig. Q3 (a). The time constants are $\tau_2 = 1$ and $\tau_1 = 0.5$, $R_2 = 1$. Sketch the response of the level in tank 2 if a unit step change is made in the inlet flow rate to tank 1. (10 Marks)

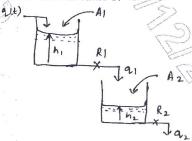


Fig. Q3 (a)

b. Derive an equation for the transfer function for an interacting system.

(10 Marks)

- 4 a. State your point of view on the following: (i) Linearization (ii) Transportation lag.
 - b. What are the characteristics of under damped system? Explain.

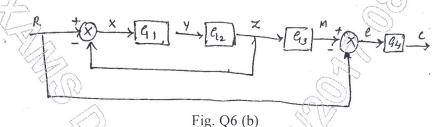
(98 Marks)

PART - B

- what do you understand by final control element? A pneumatic proportional controller is used to control temperature within the range of 60 100°F. The controller is adjusted so that the operating pressure goes from 3 psi (value fully open) to 15 psi (value fully closed) as the measured temperature goes for 71 to 75°F with set point held constant. Find gain and band.
 - b. Sketch and explain the principle of P, PI and PID controllers and obtain transfer functions.
 (12 Marks)

- 6 a. Derive an expression for servo mechanism control problem for negative feedback system.
 (10 Marks)
 - b. Determine the overall transfer function $\frac{C(s)}{R(s)}$ for the system as show in Fig. Q6 (b):

(10 Marks)



7 a. Explain the criteria for the stability for linear system.

(06 Marks)

b. Find out stability of the system for the characteristic equation:

$$3s^4 + 10s^3 + 5s^2 + 5s + 2 = 0$$

(04 Marks)

c. $\frac{1}{-1} \times \frac{1}{-1} \times \frac{1}{2+1} = \frac{1}{(S+2)(S+3)}$ $\frac{1}{1+(S-1)} \times \frac{1}{1+(S-1)} = \frac{1}{(S+2)(S+3)}$

Fig. Q7 (c)

Find: (i) Characteristic equation.

- (ii) Determine the value of Kc for which control system is stable.
- (iii) For which value of Ke the control system is on the threshold of stability.

(10 Marks)

- 8 a. Discuss flow injection analysis for measurement of substrate. (10 Marks)
 - b. What do you mean by sterilization? Explain the different ways of sterilization in a bioreactor. (10 Marks)

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