



15EE63

Sixth Semester B.E. Degree Examination, June/July 2018 Digital Signal Processing

Time: 3 hrs.

Max. Marks: 80

Note: Answer any FIVE full questions, choosing one full question from each module.

Module-1

1 Compute the N-point DFT of the signal

 $x(n) = a^n$; $0 \le n \le N - 1$

(04 Marks)

Using formula to find DFT, compute 4-point DFT of causal signal given by,

 $x(n) = \frac{1}{3} ; \quad 0 \le n \le 2$

= 0; elsewhere

Also sketch the magnitude and phase spectra. 1, 4, 3) with 12-point DFT given by X(k); $0 \le k \le 11$. Evaluate the following function

without computing the DFT $\sum_{k=0}^{11} e^{\frac{-j4\pi}{6}K} X(k)$.

(04 Marks)

OR

- A discrete time LTI system has impulse response $h(n) = 2\delta(n) + \delta(n-1)$. Determine the output of the system if the input is $x(n) = \delta(n) + 3\delta(n-1) + 2\delta(n-2) - \delta(n-3) + \delta(n-4)$ using circular convolution by circular array method. Verify the result using formula based
 - Find the output y(n) of a filter whose impulse response is given by h(n) = (3, 2, 1, 1) and input signal is given by x(n) = (1, 2, 3, 3, 2, 1, -2, -3, 5, 6, -1, 2, 0, 2, 1) using Overlap – Add method. Use 7-point circular convolution in your approach.

Module-2

An 8-point sequence is given by

x(n) = (2, 2, 2, 2, 1, 1, 1, 1).

(08 Marks)

Compute its DFT by a Radix-2 DIT-FFT algorithm. Derive the algorithm for N = 8 and write the complete signal flow graph.

(08 Marks)

OR

- The first 5-points of the 8-point DFT of a real valued sequence is given by X(0) = 4, X(1) = 1 - j2.414, X(2) = 0, X(3) = 1 - j0.414 and X(4) = 0. Write the remaining points and hence find the sequence x(n) using inverse radix-2 DIT-FFT algorithm.
 - b. If $x_1(n) = (1, 2, 0, 1)$ and $x_2(n) = (1, 3, 3, 1)$, obtain $x_1(n) \otimes x_2(n)$ by using DIF-FFT algorithm. (08 Marks)

2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice. Important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.

Module-3

a. Convert the following second order analog filter with system transfer function $H(s) = \frac{b}{(s+a)^2 + b^2}$ into a digital filter with infinite impulse response by the use of impulse

invariance mapping technique. Also find H(z) if $H_a(s) = \frac{1}{s^2 + 2s + 2}$ (08 Marks)

b. Explain bilinear transformation method of converting analog filter into digital filter. Show the mapping from s-plane to z-plane. Also obtain the relation between ω and Ω . (08 Marks)

OR

A digital lowpass filter is required to meet the following specifications:

(i) Monotonic pass band and stop band (ii) -3.01 dB cutoff frequency of 0.5π rad (iii) Stopband attenuation of atleast 15 dB at 0.75π rad. Find the system function H(z). Use bilinear transformation technique.

Design a second order bandpass digital Butterworth filter with passband of 200 Hz to 300 Hz and sampling frequency of 2000 Hz using bilinear transformation method. (08 Marks)

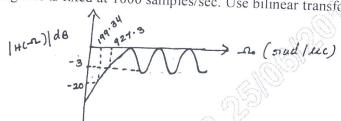
Module-4

Design a digital Chebyshev type-I filter that satisfies the following constraints:

 $0.8 \leq \mid H(w) \mid \ \leq 1 \qquad ; \qquad 0 \leq w \leq 0.2\pi$ $|H(w)| \le 0.2$ $; \quad 0.6\pi \le w \le \pi$

Use impulse invariant transformation.

Design a high pass filter H(z) to be used to meets the specifications shown in Fig.Q7(b) below. The sampling rate is fixed at 1000 samples/sec. Use bilinear transformation.



(08 Marks)

Obtain the direct form-II and direct form-II structure for the system given by

$$H(z) = \frac{z^{-1} - 3z^{-2}}{(10 - z^{-1})(1 + 0.5z^{-1} + 0.5z^{-2})}$$
 (08 Marks)

b. Draw the cascade form structure for the system given by

$$H(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} = \frac{1}{1 - \frac{1}{2}z^{-1} + \frac{1}{2}z^{-2}} \left(1 - \frac{1}{5}z^{-1} + \frac{1}{6}z^{-2}\right)$$
(04 Marks)

A digital system is given by $H(z) = \frac{1 - \frac{1}{2}z^{-1}}{\left(1 - \frac{1}{3}z^{-1}\right)\left(1 - \frac{1}{4}z^{-1}\right)}$

Obtain the parallel form structure.

(04 Marks)

Module-5

- 9 a. Explain why windows are necessary in FIR tilter design. What are the different windows used in practice? Explain in brief. (08 Marks)
 - b. The desired frequency response of a lowpass filter is given by

$$H_{d}(w) = \begin{cases} e^{-j3w} & ; & |w| < 3\pi/4 \\ 0 & ; & 3\pi/4 < |w| < \pi \end{cases}$$

Determine the coefficients of impulse response and also determine the frequency response of the FIR filter if Hamming window is used with N = 7. (08 Marks)

OR

- 10 a. Design a normalized linear phase FIR filter having the phase delay of $\tau = 4$ and at least 40 dB attenuation in the stopband. Also obtain the magnitude/frequency response of the filter (08 Marks)
 - b. Realize the system function given by $H(z) = 1 + \frac{5}{2}z^{-1} + 2z^{-2} + 2z^{-3}$ in direct form. (04 Marks)
 - c. Realize the digital filter with system function given by,

$$H(z) = 1 + \frac{1}{2}z^{-1} + \frac{1}{3}z^{-2} + \frac{1}{7}z^{-3} + \frac{1}{3}z^{-4} + \frac{1}{2}z^{-5} + z^{-6}$$
 in linear phase form. (04 Marks

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